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2.3		SeaBASS	
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3.1		in situ	AERONET

3.2		
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4.1		
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4.3		
4.4		
Rrs	in situ	
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 $L_w()$

., 2017].

[Morel et al., 1977;Gordon et al., 1994;

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[Shettle et al. 1979; Ahmad et al., 2010; Dubovik et al.,2000; Jamet et al., 2004]. , , MODIS-Aqua,

(L_{TOA}),

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[Gordon, 1978; (Ruddick et al., 2000; Moore et al., 1999; Siegel et al., 2000; Stumpf et al., 2003; Bailey et al., 2010]. L_w,

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g L_{TOA} [Gao et al., 2000; Wang and Shi, 2007; Oo et al., 2008; Wang et al., 2009 Land and Haigh, 1997; Chomko and Gordon, 1998; Stamnes et al., 2003; Kuchinke et al., 2009; Shi et al., 2016].

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., 2017; Morel et al, 1979].

(1989)

 $L_{\rm wn}$,

 $L_w()$

[Gordon, 1989].

 $L_{wn}()$

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in situ

 λ $k = 2\pi/\lambda.$

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[IOCCG (2006).; IOCCG

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(2007).; IOCCG (2008).; IOCCG (2010).; IOCCG (2012); IOCCG (2014)],

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[., 2004; ., 2009;, 2022]; 2. () [Frouin et al., 2014]; 3. () , [.,2002; Shybanov et al., 2021; ., 2021; Suslin et al., 2016; Kalinskaya et al., 2022].

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al., 1997; Chomko et al., 1998; Antoine et al., 1999].

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(CALIPSO) [Kim et al., 2018; Omar et al., 2009]. CALIPSO

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 L_{wn} . -

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: MODIS-Aqua/Terra AERONET-OC. Python. SeaDAS. , , , , . .

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1. ",05-09 , 2021.
5. XXVI
5. XXVI
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8. xXV
8. xXV
9. x, 1-5 2019.

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7. XXV		-		"	
	"	, 18-22	2017.		
8. III				«	
		»,	, 21-25 20	18.	
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2018.

10. International multidisciplinary scientific geoconference surveying geology and mining ecology management, SGEM. Bulgaria, 2019.

11. X	"				
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		, 9-11	2019.		
12. V			*		
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«SCOPUS» «Web of Science» [1-8]. 6

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«SCOPUS» «Web of Science» [Kalinskaya et al., 2018; Kalinskaya et al., 2020; Papkova et al., 2022; Papkova et al., 2020; Papkova et al., 2021; Kalinskaya et al., 2021].

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$L_w(\lambda),$

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., 1953; Mobley, 2002].

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(z)

$$\mu \cdot \frac{dL(z,\mu,\varphi)}{dz} = -c(z) \cdot L(z,\mu,\varphi) + + \frac{b(z)}{4 \cdot \pi} \cdot \int_{0}^{2\pi} \int_{-1}^{1} L(z,\mu',\varphi') \cdot p(z,\mu,\varphi,\mu',\varphi') \partial \mu' \partial \varphi' + J(z,\mu,\varphi),$$

$$c(z) = a(z) + b(z),$$
(1.1)

$$L(z, \mu, \varphi) - \mu \qquad \varphi \qquad z$$
();
$$c(z) - \qquad b(z) - \qquad ;$$

$$a(z) - \qquad ;$$

$$p(z, \mu, \varphi) - \qquad .$$

$$\int_{0}^{2\cdot\pi} \int_{0}^{\pi} p(z, \cos(\gamma), \varphi) \cdot \sin(\gamma) \cdot \partial \gamma \cdot \partial \varphi = 4 \cdot \pi , \qquad (1.2)$$

$$\cos(\gamma) = \mu \cdot \mu' + \sqrt{(1 - \mu^2) \cdot (1 - \mu'^2)} \cdot \cos(\varphi - \varphi'), \qquad (1.3)$$

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$$\mu, \mu'$$
 - ;
 φ, φ' - .

(1.1)
$$J(z, \mu, \varphi)$$

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$$J(z,\mu,\phi) = \frac{b(z) \cdot p(z,\mu,\phi,\mu_0,\phi_0)}{4\pi} \cdot S_0 \cdot \exp[-\frac{1}{\mu_0} \int_0^z c(x) \cdot dx], \qquad (1.4)$$

$$S_0$$
 –

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 γ –

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$$\tau = \int_{0}^{z} c(x) \cdot dx - z$$

$$\mu \frac{dL(\tau, \mu, \varphi)}{d\tau} = -L(\tau, \mu, \varphi) + \frac{\omega}{4 \cdot \pi} \cdot \int_{0}^{2\pi} \int_{-1}^{1} p(\mu, \varphi, \mu', \varphi') L(\tau, \mu', \varphi') d\mu' d\varphi' + \frac{\omega \cdot p(\mu, \varphi, \mu_0, \varphi_0) S_0}{4\pi} \cdot \exp[-\frac{\tau_0 - \tau}{\mu_0}],$$

$$\omega = \frac{b}{a+b} - \tag{}$$

τ

$$L(0,\mu,\varphi) = \frac{S_0\omega}{4\pi} \frac{p(\mu_0 \to \mu,\varphi_0 \to \varphi)}{1 - \frac{\mu}{\mu_0}} \left\{ 1 - \exp\left[-\tau_0(\frac{1}{\mu_0} - \frac{1}{\mu})\right] \right\}, \mu < 0.$$
(1.5)

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$$(L(z,\mu,\varphi))$$
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 $(\mu, \varphi, \mu', \varphi'),$

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$$L_{1}(\tau,\mu_{0},\mu) = \omega \frac{\mu_{0} \cdot S_{0} \cdot p(\mu_{0},\mu)}{4 \cdot \pi \cdot (\mu_{0}-\mu)} \cdot \left[\exp(-\frac{\tau}{\mu_{0}}) - \exp(-\frac{\tau}{\mu})\right],$$
$$L_{1}(\tau,\mu_{0},-\mu) = \omega \frac{\mu_{0} \cdot S_{0} \cdot p(\mu_{0},-\mu)}{4 \cdot \pi \cdot (\mu_{0}+\mu)} \cdot \left[\exp(-\frac{\tau}{\mu_{0}}) - \exp(-\frac{\tau_{0}}{\mu_{0}} - \frac{\tau_{0}}{\mu} + \frac{\tau}{\mu})\right],$$

 au_0 -

 $p(\mu_0,-\mu)$ -

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$$\frac{\tau_0}{\mu} \qquad \frac{\tau_0}{\mu_0},$$

$$\cdot$$

$$(\tau = 0) \qquad (\tau = \tau_0)$$

$$\begin{split} L_1(\tau,\mu_0,\mu) &= \omega \frac{S_0 \cdot p(\mu_0,\mu)}{4\pi\mu} \cdot \tau_0, \\ L_1(\tau,\mu_0,-\mu) &= \omega \frac{S_0 \cdot p(\mu_0,-\mu)}{4\pi\mu} \cdot \tau_0. \end{split}$$

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1980]

(1.5).

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, $p(\mu_0,-\mu) < 1$

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$$\mu \frac{dL(z,\mu,\varphi)}{dz} = \beta(z,\mu,\mu_0,\varphi) \cdot S_0, \qquad (1.6)$$

$$\beta(z,\mu,\mu_0,\phi)$$
 - , $\frac{p(\mu,\mu_0)}{4\pi}b(z)$.

$$\mu \frac{dL}{dz} = -cL + \frac{b}{2} \int_{-1}^{1} p(\mu, \mu') L(z, \mu') d\mu'.$$
(1.7)

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(1.7)
$$\mu$$
 [-1,0] [0,1],

E

$$\frac{\partial E \downarrow}{\partial z} = \frac{a + b\varphi_1}{\mu_1} E \downarrow + \frac{b\varphi_2}{\mu_2} E \uparrow,$$
$$\frac{\partial E \uparrow}{\partial z} = \frac{a + b\varphi_2}{\mu_2} E \uparrow + \frac{b\varphi_1}{\mu_1} E \downarrow,$$
$$\varphi_1 = \frac{1}{2} \int_0^1 L\mu d\mu \int_{-1}^0 p(\mu, \mu') d\mu' / \int_0^1 Ld\mu,$$
$$\varphi_2 = \frac{1}{2} \int_{-1}^0 L\mu d\mu \int_0^1 p(\mu, \mu') d\mu' / \int_{-1}^0 Ld\mu,$$



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μ φ.

 $\mu_i(z) \qquad \varphi_i(z)$

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 $\mu_i \quad \varphi_i$

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[, 1978]

$$\frac{\left(1-R_{\infty}\right)^2}{2R_{\infty}}=\frac{a}{b\varphi}.$$

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$$R_{\infty} \sim \frac{b_b(\lambda)}{a(\lambda) + b_b(\lambda)}.$$

$$x = \frac{b_b(\lambda)}{a(\lambda) + b_b(\lambda)}$$

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$$\rho(\lambda) \qquad : \rho(\lambda) = \pi \cdot L_u(\lambda, 0) / E_d(\lambda, 0), \qquad L_u(\lambda, 0)$$

-

•

 $E_d(\lambda, 0-)$ –

$$\rho = \frac{T \uparrow \cdot T \downarrow}{m^2} R_{\infty},$$

m-

[Morel et al., 1995]

,

$$L_{w}(\theta_{s},\theta_{v},\phi,\lambda,W,a,b_{b}) = E_{d}(\theta_{s},\lambda) \cdot R(\theta_{s},\theta_{v},W) \cdot \frac{f(\theta_{s},\lambda,W,a,b_{b})}{Q(\theta_{s},\theta_{v},\phi,\lambda,W,a,b_{b})} \cdot \frac{b_{b}(\lambda)}{a(\lambda) + b_{b}(\lambda)}$$





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 L_{wn} ,

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$$L_{wn}(\lambda) = \frac{L_w(\lambda)}{t_0(\lambda)\cos\theta_0},$$

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$$t_0()$$
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 $L_w() \ll \gg$

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 $L_w()$

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$$(L_{TOA})$$
 [Gordon et al., 1994]. , L_{TOA}

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$$L_{TOA}(\lambda) = [L_{r}(\lambda) + L_{a}(\lambda) + t_{dv}(\lambda)L_{f}(\lambda) + t_{dv}(\lambda)L_{w}(\lambda)]t_{gv}(\lambda)t_{gs}(\lambda)f_{p}(\lambda), \qquad (1.8)$$

;

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 $L_r()$ –

 $L_a()$ –

; $L_{f}() -$; $L_{w}() -$;

t_{dv}() –

 $t_{ds}()$ –

 $t_{gv}()$ –

, t_{gs}() –



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1.1
$$L_u^{0-}$$
 L_u^{0+} -
, L_r - (), L_d - ()
; E_d -

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1.1

 $L_w = L_u^{0+} - L_r,$

 $L_{sky}(\lambda)$ –

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 $L_{_{w}}(\lambda)$

 $L_{w}(\lambda) = L_{u}^{0+}(\lambda) - R_{f}(\lambda) \cdot L_{sky}(\lambda),$ (1.9)

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[Ruddick et al., 2019].

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[Zibordi et al., 2009] .

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, [_____, 2001].

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[Sosik et al., 1995],
$$a(\lambda)$$

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(1.10)

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$$a(\lambda) = a_w(\lambda) + a_{ph}(\lambda) + a_d(\lambda) + a_{dm}(\lambda), \qquad (1.10)$$

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$$a(\lambda) = a_w(\lambda) + a_{ph}(\lambda) + a_{ddm}(\lambda), \qquad (1.11)$$

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$$a_{ddm}(\lambda)$$
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1.12)

 C_{chl}

 $a_{ph}(\lambda) = C_{chl} \cdot a_{ph}^{spe}(\lambda)$ (1.12)

$$a^{\scriptscriptstyle spe}_{\scriptscriptstyle ph}(\lambda)$$

$$a_{ph}^{spe}(\lambda)$$
 C_{chl}

(b_b)

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[Morel, 1977]

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$$b_b(\lambda) = b_{bw}(\lambda) + b_{na}(\lambda) + b_{ba}(\lambda), \qquad (1.13)$$

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$$egin{array}{l} b_{_{bw}}(\lambda)-\ b_{_{ba}}(\lambda), b_{_{bna}}(\lambda) \ - \end{array}$$

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$$\rho(\lambda) = k \cdot b_b(\lambda)/a(\lambda)$$
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0,17 [
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., 2005]

$$\rho(\lambda) = k \frac{b_{bw}(\lambda) + b_{bp}(\lambda_0)(\frac{\lambda}{\lambda_0})^{\gamma}}{a_w(\lambda) + Chl \cdot a_{chl}^*(\lambda) + C_{ddm}e^{-\alpha(\lambda - \lambda_0)}},$$
(1.14)

$$k = 0,15 [., 2008];$$

$$b_{bw} - ;$$

$$v - ;$$

$$a_{w} - ;$$

$$a_{chl} - ;$$

$$b_{bp} - ;$$

$$k = 0,15 [., 2008];$$

$$(b_{bw} - ;);$$

$$(Bricaud)$$

$$($$

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(1.15)

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$$\rho(\lambda) = k \frac{b_{bw}(\lambda) + b_{bp}(\lambda_0)(\frac{\lambda}{\lambda_0})^{\gamma}}{a_w(\lambda) + C_{ddm}e^{-\alpha(\lambda - \lambda_0)}}.$$
(1.15)

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CZ S (Costal Zone Color Scaner),

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[Werdell et al., 2002]

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, [Junge, [Deirmendjian, 1964]

1972]

[Davies, 1974]

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(Ocean Color

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SF79) [Shettle et al., 1976]

(urban),

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(maritime)

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(*RH*).

LOWTRAN (LOW spectral atmospheric TRANsmission)

$$n(r) = \frac{dN(r)}{dr} = \sum_{i=1}^{2} \left(\frac{Ni}{\ln(10)r\sigma_{i}\sqrt{2\pi}} \right) \exp\left[-\frac{\left(\log r - \log r_{i}\right)^{2}}{2\sigma_{i}^{2}} \right],$$
(1.16)

$$N(r)$$
 — r;
 σ_i — ;
 r_i — ;
 N_i — r_i .

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[Whitby et al., 1975]



Ocean Color

(Aerosol ROboties NETwork)

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CIMEL-318.

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		(865)	(g)	(AE) (510,865)
	*	1,0	0,724–0,840	-0,0870,016
	*	0,98–0,99	0,69–0,82	0,09–0,5
	**	0,97–0,99	0,68–0,81	0,23–0,76
	*	0,93–0,99	0,603–0,76	1,19–1,53
	*	0,6–0,94	0,63–0,77	0,85–1,14
	**	0,83–0,99	0,66–0,76	0,29–0,36
*_	SF79;**-	_	(1994);	

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CIMELS

Ocean Color (2009)

[Ahmad et al., 2010].

(ω) AERONET.

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. [Ahmad et	al., 201	0]		,		
[Häne et al., 1976]				SF79		
			(m)		. (<i>r</i> _f	r_c)
	RH	30%	95%.			
	,			RH		

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$$r(a_{w}) = r_{0} \left[1 + \rho \frac{m_{w} \cdot a_{w}}{m_{0}} \right]^{3}, \qquad (1.17)$$

$$a_{w}$$
- , RH
;
 r_{o} — $RH = 0;$
 m_{o} — ;
 m_{w} — $RH;$
—

[Häne et al., 1976]

$m_w = m_o$		RH,		
20%	99%.	. [Ahmad et al., 2010]		
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RH NCEP

[Werdell et al., 2002].

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SF79.

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(70%),

(30%), . [Ahmad et al., 2010] SF79 ,

,

RH 30%

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$$n = n_w + (n_0 - n_w) \left[\frac{r_0}{r_{rh}} \right]^3,$$
(1.18)

;

$$n_w n_o RH=0;$$
 $r_o RH=0;$
 $r_{rh} RH.$

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Ocean Color

GW94 [Gordon et al., 1994]

[Bailey et al., 2006]

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LUT (Lookup table)

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SF79LUT.

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LUT

[Gordon et al., 1994].

(, 748 869 MODIS (. Moderate Resolution Imaging Spectroradiometer)),

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[IOCCG (2000)].

Gordon ,

 $\epsilon(\lambda_i, \lambda_j), \qquad \lambda_i, \lambda_j$

 $\epsilon(\lambda_{IR1}, \lambda_{IR2})$

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				,		$\varepsilon(\lambda_{IR1},$
λ_{IR2})						$\varepsilon_{\rm mod}(\lambda_{IR1},$
λ_{IR2}),	$\lambda_{I\!R1},\;\lambda_{I\!R2}$ –					
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 $\Delta(\lambda) \sim \left(2/\lambda - 1/\lambda_{IR1} - 1/\lambda_{IR2}\right)^2 - \left(1/\lambda_{IR1} - 1/\lambda_{IR2}\right)^2.$

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[Mobley et al., 2016].

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Rrs()_m= $C_1 + C_2^{-2}$

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SOA [Gordon et al, 1997; Chomko et al., 1998].

[Antoine et al., 1999]





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Rrs(),

in situ



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[Gordon et al., 1997; Chomko

et al., 1998; Antoine et al., 1999].

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in situ

() AERONET (Aerosol ROboties NETwork) [42].

Cimel-318 (CE-318).

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(GSFC NASA) [Holben et al., 1998]. AERONET (;); , , , , , ([Dubovik et al., 2000; Dubovik et al., 2000a]. AERONET 4

: Sevastopol (44,616N, 33,517E), Gloria (44,600N, 29,360E) (2019 Section_7), Galata_Platform (Galata) (43,045N, Sevastopol 28,193E) Eforie (44,075N, 28,632E). 2015 . (2.1).

> Iasi_LOASL patoria vastopol n=7 Platfo alata_Platform inthi d TUBITAK_UZAY_Ankara AERONET

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	Gloria AERONET-OC,	2010	
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AERONET-OC,	2014		13

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AERONET,

AERONET Ocean Color

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(AERONET-OC)

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7(Gloria)	Galat					Section-
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	·	(L _w),				(L _{wn})
		,			[Zibordi et	al., 2009]
		L _w .			,	L _{wn} ()
		Rrs()				F _o ()
[Thuillier	et al.,	2003].	Galata	Glori	a	
		400, 412, 443, 49	90, 510, 560	, 620, 667	7, 779, 865	1020 .
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2018	•		10750			
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7-			, AEI	RONET		
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AOT_{1020}	AOT_{870}	<i>AOT</i> ₆₇₅	<i>AOT</i> ₅₀₀	AOT_{440}
0.131±0.06	0.146 ± 0.06	0.176 ± 0.07	0.237 ± 0.08	0.264 ± 0.09
0.072 ± 0.03	0.087 ± 0.04	0.121±0.05	0.19 ± 0.07	0.22 ± 0.08

2.1

AE (

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1,5–2

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440-870

,

,

) [Basart et al., 2009].

0.75) [Gkikas et al., 2021].

.

[Lee et al., 2017].

,

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7-

NASA GMAO (Global Modeling Assimilation Office) (1

2000 . – 30 2007 .) NCEP (

NASA (Goddard Code 614 — The Atmospheric Chemistry and Dynamics Branch (T. Kucsera)). 7-(00Z 12Z)

(950 ,850 ,700 500) AERONET 0,5, 1,5, 3 5 4 4 (400, 300, 250 200 , [Schoeberl et al.,), 7, 9, 10 12 1995]. 7-AERONET (, , .) 19.10.2017 2.2 ()) 16.10.2018 ((2.2 ()) **MODIS-Aqua** (702 (19.10.2017) (16.10.2018) 2.2 (,)) 906 ,

,

[., 2015].

,

).





() 16.10.2018 7-

() 19.10.2017; () 16.10.2018

,

2.2

	MOD	IS-Terra	MODIS-Aqua		36	
			9			(
673–6	583	,				
),		

MODIS

(reprocessing), NASA 2009–2011 (https://oceancolor.gsfc.nasa.gov),

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12, 1, 3–4, 1 . MODIS

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44

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level 2 –		1	, level 3 –			
			(,	,).
	2.2	,		MODIS		

[O'Reilly et al., 1998].

		,			. ,
MODIS	Aqua	2330	250/500 /1000	36	405-14385
MODIS	Terra	2330	250/500 /1000	36	405-14385
VIIRS	SuomiNPP	3000	375/750	22	402-11800
VIIRS	JPSS-1	3000	375/750	22	402-11800

	$Rrs() (sr^{-1}),$			
MODIS	412, 443, 469, 488, 531, 547,			
555, 645, 667, 678 .	- , (⁻³)		
MODIS	<i>Rrs()</i> 2–4			
440–670 . MODIS-Aqua				
	869 .	(AE)		
	443 865 .	,		
	(),		
Ocean Color		MODIS-Aqua		
,				

AOT [, 2012].

2.3

SeaBASS

MODIS-Aqua

SeaBASS

AERONET.

SeaBASS (SeaWiFS Bio-optical Archive and

Storage System)

in situ

[IOCCG (2000)].

,

 ± 3

Rrs in situ

,

[Morel et al., 1995].

 $(5 \times 5),$

in situ.

»

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SeaBASS

:

(LAND),

(STRAYLIGHT, HIGLINT, HILT, ATMWAR), LOWLW (Lw(555) <0,15) (NAVFAILE), (CLDICE).

in situ

Rrs()

[O'Reilly et al., 2019].

51

 ± 3

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(BRDF) ~

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531, 547 555 in situ

560 .

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510

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SeaBASS

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2

(MODIS-Aqua),

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., 2020;

(AERONET-OC),

,

(AERONET).

7-

[

AERONET (Goddard Code 614), MODIS-Aqua (,

Kalinskaya et al., 2022; Papkova et al., 2022]

3			
3.1	in situ	AERONET	
AERONET-OC		$(L_{wn}())$	
	<i>Rrs(</i>).	Ocean Color	$L_{wn}()$
		AERONET-	-OC.
	Rrs()	Seal	BASS: 2
AERONET	(Gloria, Gala	uta) Ven	ise (
).			,

AERONET-	OC			<i>Rrs(</i>).
	Gloria, Galata	Venise	SeaBass	MODIS-

Aqua – 4580

Rrs()

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Rrs()

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•

	54		
()	838 . 190)
– Galata, 239 –	Gloria, 409	Venise.	
in situ Rrs()	AERONET		

$$\rho(\lambda) = f(b_b(\lambda)/a(\lambda)). \tag{3.1}$$

 $\rho(\lambda)$ $b_b(\lambda) = 2\pi \cdot \int_{90}^{180} \beta(\lambda,\theta) \cdot \sin\theta \cdot d\theta$

,

•

 $a(\lambda)$

,

[Morel A et al.,. 1977]

$$\rho(\lambda) = k \cdot b_b(\lambda) / a(\lambda) \tag{3.2}$$

(3.2)

,

k=0,15 [Bricaud et al.,

1995].

k .

1.3

AERONET-OC

•

$$\rho(\lambda) = k \frac{b_{bw}(\lambda) + b_{bp}(\lambda_0)(\frac{\lambda}{\lambda_0})^{\gamma}}{a_w(\lambda) + Chl \cdot a_{chl}^*(\lambda) + C_{ddm}e^{-\alpha(\lambda - \lambda_0)}},$$
(3.3)

;

$$b_{bw} - ;$$

$$b_{bp}(\lambda_0) - ;$$
;
$$\gamma - ;$$

$$a_w(\lambda) - ;$$
;
$$C_{chl} - ;$$

$$a_{ph}^*(\lambda) - ;$$
[, 2009]
,
$$C_{chl} = 0.75 / {}^3[$$
, 2004];
$$\alpha - C_{ddn} - ,$$

$$(0,0015),$$
 , $\gamma = 1.$

,

AERONET

,

•

.

$$f = \sum_{\lambda_i} \left[\rho_{\exp}(\lambda_i) - \rho_m(\lambda_i) \right]^2 \approx f_m = \sum_{\lambda_i} \rho_{\exp}^2(\lambda_i) \cdot \left[\frac{1}{\rho_{\exp}(\lambda_i)} - \frac{1}{\rho_m(\lambda_i)} \right]^2, (3.4)$$

,



in situ Rrs()

 $\frac{2\sigma}{\max(\operatorname{Rrs}(\lambda))}$

,

in situ

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•

•

,

			- 0,0505;			—
0,0449.	,	838	,			659
			,			21%
	. 327		Venise, 176	Gloria	156	
Galata.		,	,			
21%	in situ		Rrs()			

[, ., 2022]. , (). , , 3.2 , • AERONET 2 1,5 (Gloria Galata_Platform) 2011 2022 : , , Rrs() [IOCCG (2000); Balch et al., 2011]. , Rrs() , et al., 2019; Iglesias-Rodríguez et al., 2002]. Rrs()

PIC [Mitchell et al., 2017; Balch et al., 2018].

(CZCS) (SeaWiFS) [Brown

,

L_{wn}()

[Müller

et al., 1994; Kopelevich et al, 2014].

SeaWiFS 1998–2002 .

,

[Mikaelyan et al., 2005;

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Mikaelyan et al., 2011; Kubryakov et al., 2019].

3.1 [Lobkov, 2017].

3.1 –

(. . ⁻¹)

2005-2013 .

		—	
220.50	392.4	0	390.3
83.54	127.8	2628.93	3.04
46.10	15.85	14.7	1.15
287.50	24.90	3.4	0.5

AERONET-

OC (. . Galata_Platform Gloria/Section -7)

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59 [Zibordi et al., 2015] : , , 2008 , 1991 • [Stagl et al., 2015]. Galata-8841 Gloria–7171), (, . 412 10%. , , 42 % , , Rrs() Galata 553 2013 2021 Gloria 408 2011 2019 . , , Rrs() 961 10 • Python K–Means. «К ≫. (K) (6). • ,

means

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•

K–

AERONET

3.2.

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3.2 -

AERONET

Gloria	Galata_Platform
44	61
36	46
106	176
222	270

6

(3.1).

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49%

490

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(3.2 ()). « » ()

	412	·	0,0	0016.		Rrs()
				R	rs()		
			256	,		27%	
		555	,	,			·
,		(3.2 ()). 17	(12%	,),
	Rrs()			2,	× ·		,,
	555	((). 3.2 ())),		
		,		Gloria A	ERONET-	, –OC,	
	12			59 Rrs()		(6%).	
555		(3.2 ()).	,			ì
	5		44	(5%),	6	6). (0,6

•

•

(3.1)

%).

62



2019].

3.3 –

AERONET (Galata, Gloria)

	<i>CI</i> (412/443)	<i>CI</i> (443/555)	<i>CI</i> (443/488)	<i>CI</i> (443/547)
1	0,83±0,07	0,8±0,3	0,70±0,08	0,77±0,26
2	0,73±0,07	0,54±0,2	$0,64{\pm}0,07$	0,57±0,16
3	$0,79{\pm}0,08$	0,60±0,2	$0,66\pm0,07$	$0,62\pm0,17$
4	$0,80{\pm}0,07$	0,60±0,2	0,68±0,06	0,64±0,20
5	0,79±0,06	0,8±0,2	0,75±0,06	0,78±0,17



)

3 (164



•





65







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CI(412/443)

,

0,81±0,07,

Rrs(). *CI*(412/443)

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(

0,79 0,81 [Shybanov et al., 2022].

3

(), AERONET–OC (Gloria, Galata).

Rrs() in situ

,

,

21%

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AERONET-OC.

3.2.

,

,

CI(412/443)

0,80±0,07.

.

2022; Shybanov et al., 2022].

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4.1

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68

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(

(T)

,

[Preisendorfer et al., 1976; Plass et al, 1973].

,

(R)

$$L-$$
 ;
 μ_0- .

$$T = \frac{\pi \cdot L_{sc}}{\mu_0 F_0} + \frac{\pi}{\mu_0} \exp[-\tau / \mu_0] \cdot \delta(\mu_0 - \mu) \cdot \delta(\varphi_0 - \varphi),$$

$$L_{sc}$$
 - ;
 τ - ;
 $\delta(x_0 - x)$ - - ;
 μ - ;
 φ_0, φ - .

,

,

, *R T*

$$\hat{X} \cdot L_0 = \frac{1}{\pi} \int_{0}^{2} \int_{0}^{1} X(\mu, \varphi, \mu_0, \varphi_0) \cdot L_0(\mu_0, \varphi_0) \mu_0 d\mu_0 d\varphi_0.$$

. ,

. R T Х,

,

•

 $R,T=\frac{\pi\cdot L}{\mu_0F_0},$

$$\widehat{R} = \widehat{R}_1 + \widehat{T}_1^u \cdot \widehat{R}_2 \cdot \widehat{T}_1^d, \qquad (4.1)$$

$$R_{1}$$
 ;
 R_{2} ;
 T^{u} ;
 T^{d} .

(4.1)

[Shybanov, 2005]

$$R = R_1 + T^{\,u}T^{\,d}R_2. \tag{4.2}$$

,



P(h)

,

 P_0 .

,

 $z = P(h) / P_0, z \in [0, 1].$

,

 $d\tau_m/dz = const = \tau_m^0, \qquad \tau_m -$

•

• ,

.

 $h, \ au_m^0 \ -$

$$R_{2} = \frac{p(\cos \gamma)b(z)dz}{4\mu \ \mu_{0}},$$
(4.3)

$$b(z) - ($$
) Z;

$$p(z, \cos \gamma) - ,$$

$$\cos \gamma = -\mu_1 \cdot \mu_2 + \sqrt{1 - \mu_1^2} \sqrt{1 - \mu_2^2} \cos \varphi.$$
(4.2) (4.3),

•

—

•

$$\frac{dR}{dz} = T^{u}(z) \cdot T^{d}(z) \cdot \frac{p(\cos\gamma) \cdot b(z)}{4\mu_{0}\mu}.$$
(4.4)

, ...
$$p(\cos\gamma) < 1$$
. $T_1 \quad T_2$ 1,

,

.

$$a(z) = \frac{d\tau_a(z)}{dz} \cdot (1 - \Lambda(z)),$$

•

,

,

 $au_a(z)$ – Z, $\Lambda(z)$

•

$$g(z) = \frac{1}{\tau_a^0} \frac{d\tau_a(z)}{dz} = \frac{h_m}{h_a} z^{\frac{h_m - h_a}{h_a}}, \qquad \tau_a^0 - , \quad h_m \approx 8 \, km, \, h_a \approx 1.2 \, km - 1.2 \, km$$

() -

$$T^{u}(z) = \exp\left[-\frac{1}{\mu}\int_{0}^{z}a(x)dx\right], T^{d}(z) = \exp\left[-\frac{1}{\mu_{0}}\int_{0}^{z}a(x)dx\right].$$
(4.5)

$$\frac{dR}{dz} = \frac{p_m(\cos\gamma) \cdot b_m(z)}{4\mu_0\mu} \exp\left[-\left(\frac{1}{\mu_0} + \frac{1}{\mu}\right) \cdot \int_0^z a(x)dx\right] + \frac{p_a(\cos\gamma) \cdot b_a(z)}{4\mu_0\mu} \exp\left[-\left(\frac{1}{\mu_0} + \frac{1}{\mu}\right) \cdot \int_0^z a(x)dx\right],$$

$$m, a -$$

$$,$$

$$, \qquad , \qquad a(z) = 0$$

$$a(z) \neq 0$$

$$r = R(a(z) = 0) - R(a(z) \neq 0).$$

$$r = \frac{p_m(\cos\gamma) \cdot \tau_m^0(\lambda)}{4\mu_0\mu} a_0(\lambda) \cdot \left(\frac{1}{\mu_0} + \frac{1}{\mu}\right)_0^1 \int_0^z g(x) dx \cdot dz.$$
(4.6)

•

,

•

$$a_{0}(\lambda) = (1 - \Lambda(\lambda))\tau_{a}^{0} - \qquad .$$

$$, \qquad (4.6)$$

$$. \qquad : 1) \qquad g$$

$$1 \quad [\qquad ., \ 2020], \quad \int_{0}^{z} g(x)dx < 1$$

$$; \ 2) \qquad (1 - \Lambda(\lambda)) <<1; \ 3)$$
•

,

,

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,

$$\frac{p_m(\cos\gamma)}{\mu_0\mu} \left(\frac{1}{\mu_0} + \frac{1}{\mu}\right) -$$

,

,

,

 $\Lambda(\lambda)$

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•

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,

 $a_0(\lambda)$.

$$au_m^0(\lambda)$$
. , $au_m^0 pprox \lambda^{-4}$.

•

•

,

,

$$\delta = \frac{\tau_m \cdot M_m}{4\mu\mu_0} = \frac{\tau_m}{4\mu\mu_0} \left(1 - \frac{h_a \tau_a^a}{h_a + h_m} \left(\frac{1}{\mu} + \frac{1}{\mu_0}\right)\right).$$
(4.7)

,

MODIS-Aqua

in situ

•

AERONET

:
$$a_0 = (1 - \Lambda)\tau_a^0$$
. ,
A AERONET 4
(1020 , 870 , 675 , 443), (412 ,
490 , 532 , 547 , 555 , 667) Python.
(4.7),
c ,

AERONET.

[Penndorf et

al, 1957]

 $\tau_{\rm m} = \frac{1.545 \cdot 10^{10}}{\lambda^{4.086}}.\tag{4.8}$

	,	in situ		AERONET	(, Λ	,μ
$\mu_0)$	(4.8) (4.	.7)				
		,				
			()
			•			
	(4	4.7).				
					in sit	и
	Rrs()		(7	٨).		
				A	ERONE'	Т
	MODIS-Aqu	1a.				
	(<i>PCC</i>) [, 2007].		,	412

0,729 (73%) 443

0,673 (67%),







4.2.

()

SeaBASS

Rrs()



4.3) (

AOT(869)

12.09.2017 (a))()(

Rrs(412

)<0

: SeaDAS).

4.1 -

(

4.3 –

MODIS-Aqua

08.09.2017 (

4.3)

(08.09.2017)

(12.09).

Rrs()

Dury()	410	442	460	100	521	517	555	615	667
Krs()	412	445	409	488	551	547	555	045	00/
08.09	0,0031	0,0040	0,0046	0,0049	0,0039	0,0034	0,0030	0,0004	0,0003
12.09	-0,0002	0,0020	0,0033	0,0036	0,0030	0,0026	0,0023	0,0002	0,0002

[Kalinskaya et al., 2022].

Rrs()

[., 2022]. MODIS-Aqua

18–19.10.2017 (4.4).



) 18.10.2017;) 19.10.2017

2017

[Papkova et al., 2022].

Rrs()

(19.10.2017).

:

Rrs()

2

(19.10.2017).

Rrs()

(13.10.2017)

(13.10.2017) 19.10.2017 ,

, (4.2). ,

,

[

•

(13.10.2017)

(19.10.2017)

Rrs()	412	443	469	488	531	547	555	645	667
13,10	0,0018	0,0024	0,0029	0,0031	0,0025	0,0022	0,0019	0,0003	0,0003
19,10	-0,0004	0,0022	0,0037	0,0040	0,0041	0,0038	0,0034	0,0017	0,0017

Rrs()

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., 2021].

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Rrs()

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AERONET

,

<i>Rrs()</i> (MODIS-Aqua)

7	,
•	

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•



11.09.2017 () 10.08.2016 (



)

		Ocean	Color	
4.5.		,	,	
04.11.2014()	30.09.2016 ()

•

MODIS-Aqua

in situ AERONET , : (*AOT*), (AE),

 $(\Lambda(z)).$

((-//)

AOT



4.3 -

MODIS-Aqua

,

49
80
70
133
332

	in situ	
862	MODIS-Aqua	AERONET
72 %	· ,	
	37%	
	AOT).	

,

,

in situ

, *AOT*

(

4.4).

4.4 –

(

	(Gloria, Galata)				
	•				
		AOT			
1020	$0,039\pm0,005$	$0,040\pm0,007$	0,072±0,01	0,056±0,002	
870	0,051±0,007	$0,052{\pm}0,008$	0,091±0,02	$0,076\pm0,008$	
667	0,077±0,01	0,081±0,02	0,133±0,03	0,111±0,01	
551	0,110±0,01	0,116±0,03	0,184±0,05	0,149±0,02	
532	0,117±0,03	0,123±0,05	0,195±0,06	0,158±0,02	
490	0,132±0,02	0,139±0,03	0,217±0,08	0,185±0,03	
443	0,157±0,02	0,163±0,03	0,256±0,08	0,206±0,02	
412	0,175±0,03	0,180±0,05	0,283±0,10	0,239±0,05	
		AE			
440-870	1,688	1,757	1,499	1,541	
440-865	1,775	1,730	1,535	1,540	



, PCA

•

[Pearson, 1901; Fre het, 1948].

,

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in situ

AERONET

MODIS-Aqua.





PCA



MODIS-Aqua

AERONET

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4.7.

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Rrs()



4.5 –

(MODIS-Aqua)

	R^2
$9 \cdot 10^8 \lambda^{-3.574}$	0,96
$2 \cdot 10^6 \lambda^{-2,73}$	0,91
$7\cdot 10^9 \lambda^{-4,087}$	0,85
$3 \cdot 10^2 \lambda^{-1,367}$	0,24



3.1. 3.2

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,

 λ^{-4} .

•

level 2,

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•

Ocean Color

()

$$Rrs_{m}(\lambda) = Rrs_{sat}(\lambda) + k \cdot \lambda^{-4}, \qquad (4.9)$$

$$Rrs_{sat}(\lambda) - \qquad ,$$

Rrs()

;

,

		- [., 2021; Suslin e	et al., 2016;
Suslin et al	1., 2007].			
	(_	412
)	*		,	
				(
3.2).	k			
,			2	412

443

,

 $k = \frac{CI(\frac{412}{443})Rrs_{sat}(443) - Rrs_{sat}(412)}{(412^{-4} - CI(\frac{412}{443})443^{-4})}.$ (4.10)

,

(

, (4.10) k

,

443, 488, 531, 547, 555 667

AERONET

3.1)

•

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332

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4.8).



()







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(

;



()



(



4.9 – *Rrs()* MODIS AERONET-OC, 412 (), 443 (), 488 (), 547 () .



18%

(), 80% () (4.10).



()

4.10 -

CI

AERONET-OC,

.

0,25

MODIS



869 443 412 7 (,) , , 7()



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Rrs(),

•







4.11 – MODIS-Aqua 27 2020 .: () , () *CI* (547/443), () *Rrs*(412), () *Rrs*(443) (SeaDAS)

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Rrs()			(
4.12).	4.12	,	

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	(. 4.13).		,
			[Shybanov et	al., 2022].
4.4	Rrs	in situ		
	Ň	Rrs()	116	« .
	». 90	2021		
	,			Rrs()
		[., 2021;	Korchemkinaet al.,
2022].	,		Rrs()	412
443			0,80±0,03.	
		,	,	AERONET- ,
			(3.2).
			(
)	Rrs()	MOE	DIS A	qua Terra.
			(R2	.022).
			in sit	
Rrs()		4.14 (). ,	4.14 ()
		Rrs (412	Rrs	s(412): <i>Krs</i> (443)
	aot869 (869).



		,		
	: (1)	aot869	0,05	0,25,
(2)	<i>Rrs</i> (412): <i>Rrs</i> (443)		,	0,76.
	aot869			
	4.6.			
	4.6 –			Rrs(),
	4.14			

		aot869	
	in situ		
MODIS– Aqua	18	0,054	1,99
MODIS-Aqua	50	0,100	1,46
MODIS– Aqua	51	0,096	1,55
MODIS– Terra	33	0,195	0,58

,

(4.6) (4.15).



4.15

•

Rrs()

, ,	. 4.1 ,
	, λ ⁻⁴ .
,	, (4.9). , (<i>CI</i>) 412 443 ,
,	S.2. , Rrs(). <i>level</i> 2.
R ² 2 412 , 531–555	<i>Rrs(</i>). 443 488 ,
Rrs(). <i>Chl–a,</i> (60%	, AERONET 412).
2022 ; Papkova et al., 2020; Kalinskaya et al., 2022; Papkova et a	[., ., 2021; , 2022; d, 2022; Shybanov et al., 2022].

(MODIS-Aqua),

,

,

(AERONET–OC), AERONET,

(AERONET).

•

)

in situ

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AERONET-OC

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,

AERONET-OC,

(

••

•

1.3, 13% , CI(412/443) , 0,80±0,07, AERONET-OC, 116 ≫. , 20%.

> 4.1. • , λ^{-4} . ,

> > Rrs(), PCA

, λ ,

, $y = 9 \cdot 10^8 \lambda^{-3.574}$. , (4.9).

> (CI) 412 443 ,

3.2.

,

MODIS-Aqua

(PCA)

,

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Rrs

•

	R^2						Rrs()
	2	412	•			443 4	88 ,
		531-555					
		Rrs()		,			
	Chl–a,					AERO	NET-OC
(60%	412).		
116		« .		»,			
	4.4.						
		,					
().				AER	ONET
	Oce	ean Color			,	in situ	
				_			

•

,

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$$, \cdot -2 \cdot -1$$

 $, \cdot -2 \cdot -1$

 $L_{TAO}-$

 L_w –

SMA –

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CZ S – Costal Zone Color Scaner

CDOM –

MODIS – Moderate Resolution Imaging Spectroradiometer

AERONET – Aerosol Robotic Network

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